



RobAIR : Robotics Guide



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Presentation of the project

Introduction and general aspects

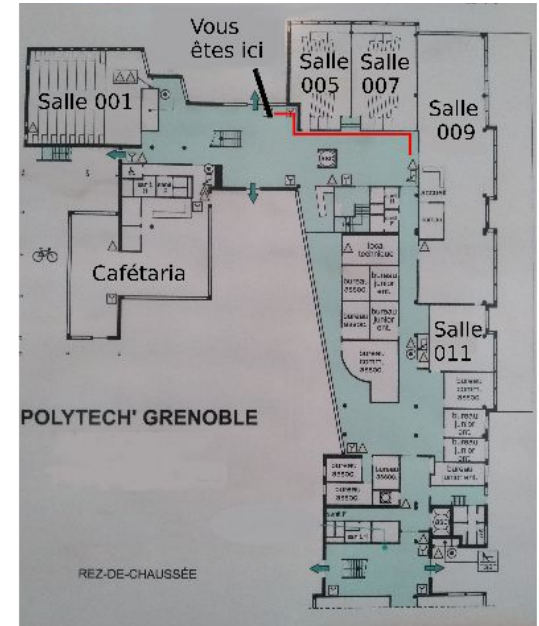
What is RobAIR?

- Telepresence robot platform based on Grenoble
- Intended for teaching robotics



Objectives of this project

- Provide a map of the floor of the building where RobAIR is.
- Provide the path to this room
- Be driven to the room



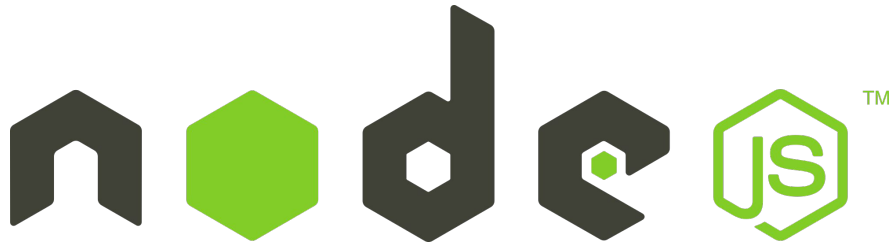


How does it work?

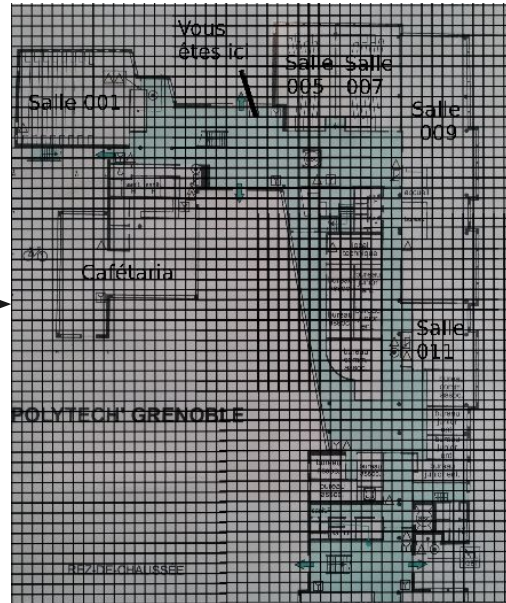
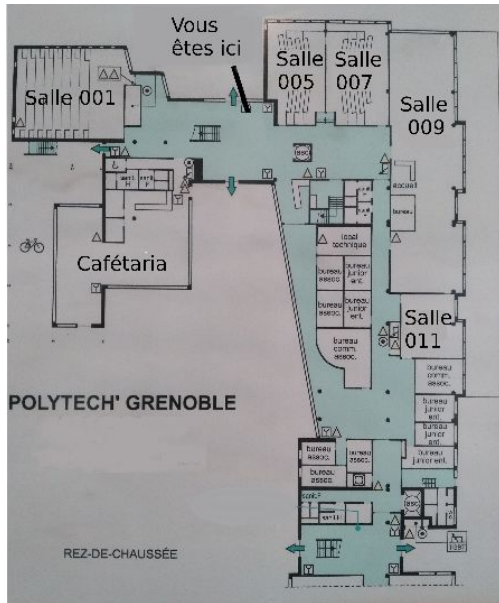
Technical aspects



Technologies used



Map preparation for Dijkstra



The map is written as a sequence of 0 and 1



Interface overview

Robair Client

← → ↻ 🏠

🔍 Saisir un terme à rechercher ou une adresse

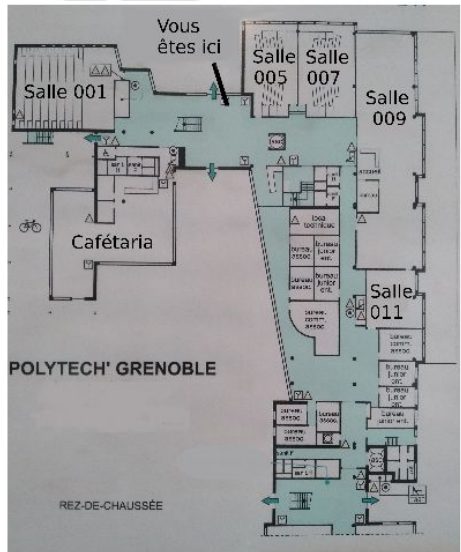
🔍 Rechercher

☰ 📄 ASP ☰

RobAIR

Veuillez choisir la salle vers laquelle RobAIR doit vous guider :

Souhaitez-vous que RobAIR vous y amène?



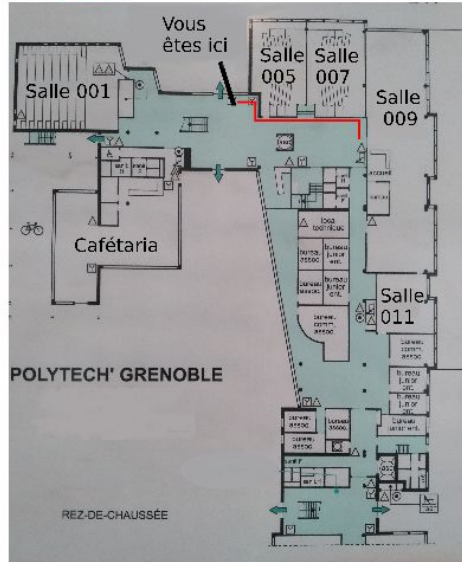
Customer interface



Veuillez choisir la salle vers laquelle RobAIR doit vous guider : 009

Souhaitez-vous que RobAIR vous y amène?

ok Reload



Customer interface with the path to the room 009



Conclusion



Difficulties

- Technologies
- Installation
- FabLab availability

Benefits

- Discovery of JavaScript
- Discovery of ROS
- awareness of current technology (LiDar, Intel Movidius)



Thank you for your attention

Demonstration time